

2001P02943WOUS  
Boller *et al.*  
Application No.: 10/668,971

### AMENDMENT TO THE CLAIMS

The text of all pending claims, (including withdrawn claims) is set forth below. Cancelled and not entered claims are indicated with claim number and status only. The claims as listed below show added text with underlining and deleted text with ~~striketrough~~. The status of each claim is indicated with one of (original), (currently amended), (cancelled), (withdrawn), (new), (previously presented), or (not entered).

The following listing of claims will replace all prior versions, and listings, of claims in the application:

#### Listing of Claims:

1. (previously presented) A method for filling, removing, and transporting a receiving container for sorted items, a number of which are filled along a sorting path with sorted items at individual destination points, the sorting items being of the same type, and after filling are transported away from the destination points by way of a transport facility, comprising the steps of:

- placing an empty receiving container on a holder;
- inserting the container and holder on a guide beneath a destination point;
- withdrawing the receiving container and holder at least once for filling with sorted items, a withdrawing direction being crosswise with respect to a sorting path direction and opposite to an insertion direction;
- reinserting the container and holder after the filling;
- raising the container from the holder in response to a control command, the raising being performed by a lift;
- withdrawing the holder in an opposite direction to an insertion direction;
- lowering the receiving container via the lift onto the transport facility situated beneath the destination point;
- transporting the receiving container away from the destination point via the transport facility; and
- moving the lift into an idle position.

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2. (original) The method according to claim 1, further comprising the step of replacing the container with another container at the destination point.

3. (original) The method according to claim 1, further comprising the steps of:

- prior to the step of lowering, determining if a space below the container is occupied, and
- if the space is occupied, not performing the step of lowering.

4. (currently amended) A system for filling, removing, and transporting a receiving container for sorted items, comprising:

- a sorting path along which the container can be filled with the sorted items;
- a plurality of destination points positioned along the sorting path, the destination points providing the sorting items to the container;
- a transport facility located proximate to the sorting path and destination points, the transport facility transporting the container from a destination point;
- a holder for accommodating the container therein;
- a guide facilitating lateral movement of the holder beneath the destination point and configured to position the container in and out of a filling position, the filling position being a position wherein the container can be filled with the sorted items; and
- a lift located proximate to the container, the lift facilitating raising and lowering of the container from the holder to the transport facility.

5. (original) The System according to claim 4, further comprising means for moving the container from a filling position into and out of a ready position beneath the destination point.

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6. (previously presented) The system according to claim 4, wherein the holder comprises a holding frame facilitating accommodation of the container and a handle facilitating movement of the holder.

7. (previously presented) The system according to claims 4, further comprising at least one actuation element effecting initiation of a control command for removal and transportation of the receiving container.

8. (original) The system according to claim 5, wherein the lift further comprises means for first raising the receiving container from the ready position and, after the holder has moved into the filling position, lowering the container onto the transport facility.

9. (original) The system according to claim 5, further comprising control elements for controlling and monitoring the removal and transportation of the receiving container.

10. (original) The system according to claim 9, wherein at least one control element comprises means for detecting a presence of the receiving container in the ready position.

11. (original) The system according to claim 9, wherein at least one control element comprises means for detecting the holder in the filling position.

12. (original) The system according to claim 9, wherein at least one control element is located at an uppermost and lowermost position of the lift and further comprises means for detecting if the lift is in the uppermost and lowermost positions.

13. (original) The system according claim 9, wherein at least one control element comprises means for detecting an idle position of the lift.

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14. (original) The system according to claim 9, wherein at least one control element comprises means for controlling and monitoring the removal and transportation of the receiving container on the transport facility.

15. (original) The system according to claim 4, further comprising a transport facility section composed of a plurality of destination points.

16. (previously presented) The system according to claim 9, wherein at least one control element is located at a beginning and end of a transport facility section.

17. (previously presented) The system according to claim 9, wherein at least one control element is located at a beginning or end of a transport facility section.